

INTRAOPERATIVE SPINAL NAVIGATION USING BRAINLAB NAVIGATION MACHINE		
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1.0 Introduction

The spinal navigation system receives and transmits data about anatomy of the spine and placement of implants, displaying the information on a computer screen where the surgeon can view it. The navigation system is composed of a computer workstation with a screen, software, a tracking system, and surgical instruments. The tracking system is composed of small reflective spheres that are attached to the patient (spine reference array) and tracked by an optical camera to register the location of the anatomical structures. The computer develops a model of the spine and projects the image onto a monitor. The surgeon touches parts of the patient's anatomy with a pointer so the computer can identify and register those points in its memory, including specific bone structures, the anatomy, the motion and alignment of the patient's normal anatomy, and the optimal joint alignment. With this information, the computer can guide the surgeon in placing the pedicle screws.

2.0 Definition of Guidelines

Spinal navigation is an image-guided technology for spinal surgery, which delivers more accurate pedicle screw placement by receiving and transmitting data about anatomy of patient's spine.

3.0 Applicable to

This guideline affects all theatre nurses, members involved in spinal surgery in the Operating Theatres at CHI Crumlin.

4.0 Objectives of Guidelines

This document provides guidance to theatre nurses in the use and care of navigation equipment and instruments. Proper care and handling of navigation equipment and instruments are essential to patient and personnel safety.

5.0 Definition / Terms

Spinal Navigation - an image-guided technology for spinal surgery, which delivers more accurate pedicle screw placement

Spinal deformity - a curvature in the spine where the alignment is outside of defined normal limits.

3D imaging - visual representations of the interior of the body through which a surgeon can see a true picture of the anatomy.

Pre-Registration of images - The process of aligning patient anatomy with the radiographic imaging before surgery.

Intra-operative registration of images - The process of aligning patient anatomy with the radiographic imaging during surgery.

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6.0 Procedure

Role of Circulating Nurse

- Operating Room Set Up
 - Call radiographer to notify navigation case pre op and present for case, on extension 6455.
- Undock the monitor and the camera by pushing the docking pedal down and pull apart.
- Plug in the machine.
- Connect the monitor to the camera.
- Insert the intraoperative data cable from the 3D Ziehm on to the screen.
- Switch on the mains power.
- The circulating nurse must secure the drapes with sleek to the table in order to keep the underside of the table clear during screening. A scissors must be available at all times to use in case of emergency to cut the frape and to transfer the patient.

6.1 Software Set Up

- Switch on the mains power switch and wait until camera warms up.
- Select 3D navigation under spine & trauma.
- Select "spine and trauma".
- Refresh to ensure that the camera, monitor and 3D Ziehm are connected.
- Select new scan.
- Make sure that all three reflective marker spheres in the spine reference array are visible on screen (Yellow Colour).
- Radiographer performs the collision check and once completed ensure the three reflective marker spheres in the spine reference array are visible on screen (Yellow Colour) and the six reflective marker spheres on the C-arm drapelink appears on screen (Purple).
- The radiographer will carry out a spin. If the thoracic spine is being visualized, the anaesthetist will be asked to do a breath hold on patient before the spin. Once the spin is completed, the data will automatically be transferred and appears on to the BrainLab navigation monitor.
- Adjust colour and contrast as required. Switch off canopy lights to enhance viewing.
- Select patient orientation and confirm patient's position (prone).
- Select surgeon's position on screen left side if surgeon is on the left and vice versa. If camera is at the head end, select head / feet. If camera is at the foot end, select foot / head. Confirm the setting with the surgeon.
- The surgeon will verify accuracy.

6.2 Role of the Scrub Nurse

- Cover the Ziehm C-arm with the sterile Ziehm C-arm cover.
- Disposable, sterile reflective marker spheres are attached to reference arrays, C-arm drapelink
 and pointer before calibration or use in surgery to enable the system to detect the position of
 the patient and instruments in the surgical field.
- Fix the C-arm drapelink on to the C-arm.
- Marker spheres must be counted as per the CHI at Crumlin perioperative count policy.

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- Hand the radiolucent clamp, spine reference array, extension attachment to the surgeons.
- Have pointer prepared with three radiolucent spears attached. This must be covered during the collision check.

6.3 Post Procedure

- Remove all reflective marker spheres and dispose as per CHI at Crumlin Waste Disposal Policy.
- All reusable instruments must be sent to HSSD for decontamination and sterilisation.

6.4 Cleaning, Disinfection and Sterilisation

- Wipe the screen and camera with square gauze and sterile water and dry appropriately.
- Clean the rest of the monitor cart and camera post with detergent and dry appropriately.
- Apply screen protection provided and the monitor and camera is ready for docking and transport.

6.5 Docking and Transport

Monitor Cart - Loosen all locking knobs. Move the upper arm out of the way of the lower arm.
 Rotate the lower arm to the position indicted until the parking symbols align. Tighten the locking knob.

6.6 Camera

- Locate the park symbol on the camera post. Press the button on the telescopic post handle to move the post into the parking position.
- Fold the camera arm down with the handle until firmly aligned to the post.
- Rotate the camera to the side with the handle.
- Fix the camera to the post with the Velcro protection cover strap.
- Push the camera cart into the monitor cart quickly until the docking pedal pops up (Please make sure that the docking pedal is down before docking).

6.7 General Rules for Use

- Set up the operating room prior to surgery to ensure that the camera and screen are in working condition and ready for navigation.
- The equipment and instruments are accurate and sensitive medical devices and must be handled with extreme care.
- Do not use damaged or corroded instruments.
- The marker spheres of the pointer and the array must be visible to the camera at all times during registration and navigation.
- Only use clean and dry marker spheres. Wet or soiled marker spheres must either be cleaned and dried before further use or replaced. Only use a soft cloth moistened with sterile water to clean the surface of soiled spheres. Ensure that the cleaned marker spheres is absolutely dry before use.
- Do not mask or cover any marker spheres, otherwise navigation is not possible or may be inaccurate.
- Always store pointers in their designated inserts in the pointer gauge to prevent pointer damage.
- Electrical cords and plugs should be checked for fraying and damage prior to each use.

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- Following use, personnel should turn of the BrainLab navigation machine, clean all reusable parts and inspect these parts according to the manufacturer's written instructions.
- Inaccurate instruments must be returned to BrainLab for testing.
- If troubleshooting fails, call clinical engineering on bleep 8445.

7.0 Implementation Plan

- Initial education will include Education Programme (Appendix 1), Hands on Training (Appendix 2), Demonstration (Appendix 3).
- Ongoing continuing education regarding the use of BrainLab navigation machine should be provided to all theatre nurses.
- A brief set of clearly readable operating instructions should be readily accessible with the BrainLab navigation machine. These instructions should be placed or attached to the BrainLab navigation machine for reference Manufacturer's operational manual should be readily available.
- It is the responsibility of individual staff member working in the perioperative setting to ensure that they are competent, accountable and responsible in the safe use of BrainLab navigation machine.

8.0 Evaluation and Audit

Monitoring of compliance is an important aspect of procedural documents. Staff competency must be reviewed on a regular basis and ongoing training will be provided to maintain competencies.

9.0 References

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10.0 Appendices

Appendix 1 - Education Programme Overview

Date:	Time	Activity	Remarks
	08:00 – 09:00am	Basic Spinal Anatomy and its Importance in Spinal Navigation Assessment	
	09:00 – 10:00am	Introduction to Spinal Navigation	
	10:00 – 11:00am	Theory and Hands on Training Instruments	
		OR Set Up	
		Software Set Up	
	11:00 – 11:15am	Coffee	
5 4	11:15 – 13:00	Theory and Hands on Training	
Day 1		Instrument Calibration	
	13:00 – 13:30	Automatic Registration Lunch	
	13:30 – 13:30 13:30 – 15:00	Theory and Hands on Training	
	13.30 – 13.00	Manual Registration:	
		Paired Point Matching	
		Manual Registration:	
		Region	
	15:00 – 15:15	Coffee	
	15:15 17:00	Theory and Hands on Training	
		Per op CT- Data	
		Transfer	
		Trouble Shooting	
		Aftercare of BrainLab Machine	
Day 2, 3		Training Live Case	
Day 4, 5, 6		Training – Under Supervision	
Day 7, 8, 9, 10		Training Independent	

N.B. The agreed timeframe for completing this training programme is 3 weeks. Day 1 will include lecture, demonstration and hands on training. Day 2, 3 will be observation in theatre, Day 4, 5, 6 will be training under supervision and day 7, 8, 9 & 10 will be independent training.

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Appendix 2 - Training Record

	Date:			
Procedure	Observed	Performed Under Supervision	Performed Independently	
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Appendix 3 - List of Instruments and Equipment – Demonstrated & Used

Equipment	Demonstrated	Used	
3D C-Arm			
Camera			
Monitor			
C-Arm Drapelink			
Reflective Marker Sphere			
Sterile Remote Control			
Instrument Calibration Matrix			
Pointer			
Radiolucent Clamp			
Spine Reference X Clamp			
Wrench			
Reference Array			
Instrument Adapter Clamp			
Instrument Adapter Array			
Tool for Instrument Adapter Array			

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Theoretical Assessment	Sign & Date		Remarks		
Have read and signed relevant local SOP.		// 20 _			
Have attended training and educational sessions on spinal navigation.		// 20			
Have updated competency book and training record, on site and readily available.		// 20			
Have attended radiation safety training.		// 20			
Clinical Assessment	Observed	Participated	Supervised	Comments	
Role of Scrub Nurse					
Covering the Ziehm C-Arm					
Attach disposable, sterile					
reflective marker spheres to					
reference arrays, C-arm					
drapelink and pointer					
before calibration or use in					
surgery.					
Fix the C-arm drapelink on					
to the C-arm					
Marker spheres must be					
counted as per the CHI					
Crumlin Perioperative					
Count Policy.					
Correct handling of the					
radiolucent clamp, spine					
reference array, extension					
attachment and wrench.					
Software Set Up					
Camera warm up					
Set up monitor					
Demonstrate knowledge on					
collision check by					
radiographer					
Demonstrate understanding					
on breath holding by					
anaesthetist					
Automatic transfer of data					
on to the BrainLab					

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navigation monitor			
Adjust colour and contrast			
as required			
Select patient orientation			
and confirm patient's			
position (Prone)			
Select surgeon's position;			
left side if surgeon is on the			
left and vice versa			
If camera is at the head			
end; select head/feet.			
If camera is at the foot end;			
select foot / head			
Verification accuracy by			
surgeon			
Docking the Transport			
Monitor cart			
Camera			
Dock the camera cart into			
the monitor cart			
Cleaning, Disinfection and	Sterilisation		
Remove all reflective			
marker spheres and			
disposal as per CHI			
Crumlin Waste Disposal			
Policy.			
All reusable instruments			
must be sent to HSSD for			
decontamination and			
sterilisation.			
Wipe the screen and			
camera with square gauze			
and sterile water and dry			
appropriately.			
Apply screen protection			
provided and the monitor			
and camera is ready for			
docking and transport.			

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